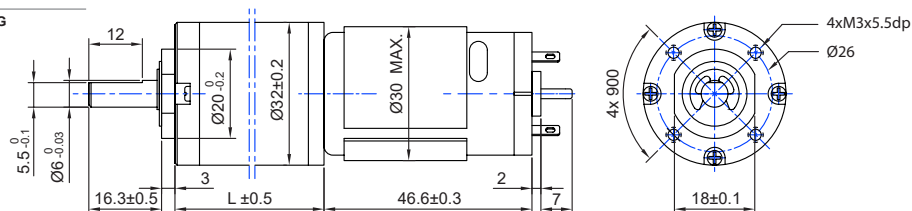


DRAWING
(mm)

PHOTO



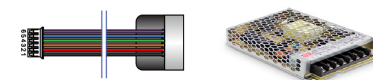
MODEL NO. DESIGNATION EXAMPLE

1 - 2 - 3 - 4

1 = empty → sleeve bearing
 1B = ball bearing
 2F = emc filter varistor / capacitor
 3E = magnetic encoder
 4 = empty → no encoder rear cover cap
 4C = magnetic encoder rear cover cap

PD1230 - VOLTAGE - REDUCTION - B - F - E - C

OPTIONS ENCODERS AND POWER SUPPLIES

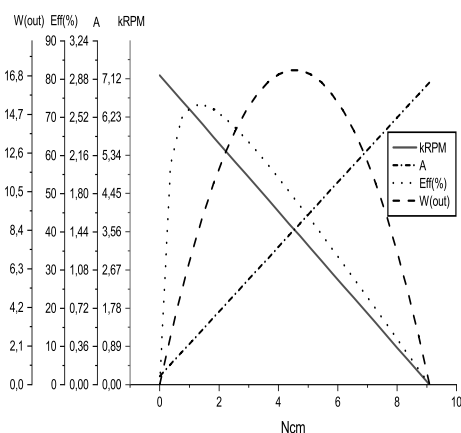


● C = customizations are offered on demand even for smaller quantities. Typical customizations indicated with green dot at column end. Please contact us for any customization request

GEAR MOTOR DATA															C
Gear reduction		1:5	1:14	1:19	1:27	1:35	1:51	1:71	1:100	1:139	1:189	1:264	1:516	1:721	
Nominal torque ^ gear box limit	mNm	53.0	117.7	166.7	235.4	304.0	392.3	539.4	647	981	1177	1177	1177	1177	
Nominal speed	rpm	1170	445	320	229	176	121	87	60	45.0	34.0	25.0	13.0	9.6	7.2
Peak torque ^ gear box limit	mNm	588	1177	1177	1765	1765	2354	2354	2942	2942	3530	3530	3530	3530	3530
Mechanical power	W	5.204	3.849	3.921	3.961	3.933	2.990	2.956	2.447	2.780	2.101	1.545	0.803	0.593	0.445
Efficiency gear head	%	80	70	70	70	70	60	60	60	60	50	50	50	50	50
Length gear box = L	mm	20.6	27.0	27.0	27.0	27.0	33.4	33.4	33.4	33.4	39.8	39.8	39.8	39.8	39.8
Weight	g	211	231	231	231	231	256	256	256	256	282	282	282	282	282

GEAR MOTOR COMBINED DATA			C	GEAR BOX SHAFT DATA			C	GEAR BOX SPECIFIC DATA			C
Service life brush wear	500 h continuous operation		●	Radial play thrust play	mm	≤ 0.05 ≤ 0.3		Material gear stage	Ratio 1:5 sintered steel		●
Performance tolerances	% ± 15			Shaft axial load	N	24.5		Material > 1:5 ratio / stage	POM first + sintered steel		●
Operating temperature	-10....+60 °C		●	Radial load	N	34.3		Direction of rotation	CCW or CW by reversed V polarity		
IP code	20			Press fit force max.	N	98.1		Assembly front bell	mm	Maximum screw depth 4.0	
Manufacturing standard	ISO9001 ISO 14001 TS16949			Backlash no load	°	≤ 2.5					
Compliance	RoHS and REACH			Bearing type shaft material		Ball bearing AISI 1144					
Label CE UL	CE no UL no			Motor pinion material shape		Steel straight	●				

24 VOLT MOTOR PERFORMANCE GRAPH



MOTOR SPECIFIC DATA

Nominal voltage	V	24 (12 V separate data sheet)	●
No load speed	rpm	7200	
Nominal speed	rpm	6160	
Nominal torque	Ncm	1.27	
Nominal current	A	≤ 0.08	
Nominal mechanical power	W	8.5	
Stall torque	Ncm	9.09	
Starting current	A	2.85	
Motor commutation		Carbon brush	●
Motor rotor stator		Iron rotor Ferrit magnet	
Varistor emc	V	26-38	●
Capacitor emc	V	24	
Resistance	ohm	8.77	
Inductance	mH	4.1	
Insulation class		F	●

GEAR MOTOR RANGE STANDARD AVAILABILITY

Nominal voltage	V	2.4 - 24	separate data sheet
Nominal mechanical power	W	0.023 - 25	separate data sheet
Diameter	mm	12 - 42	separate data sheet
Feedback encoder	Hall Optical	see below	

ACCESSORIES

Power supplies LRS	V	3.3 - 48	separate data sheet
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ENCODER OPTIONS		MAGNETIC HALL SENSOR		OPTICAL SENSOR		C
Pulses per revolution		7 x 2		(100 200 256 360 400 500) x 2		●
Channels phase shift			2 90° ±(1/6)T			
Encoder rear cover		Cover cap in ABS plastic		Zink alloy		
Sensor technical data		Refer externally to brand and part UTC-SK1816				
Size		Ø 30 x 12.1		D19+4.5 x W30 x H40 mm		
Harness connector		JST PHR-6 P=2-6P		JST SMR-05V		●
Harness cable		UL1007 AWG24 100 mm		UL2464 AWG24x4C 195 mm		●
Connection		BLK M- RED M+ BRN Vcc GRN GND BLU A VIO B		RED Vcc GRN GND BLK A WHT B		
Supply voltage Vcc		min.3.5 ref - max. 20 V		5 ±10% V		
Supply Current Ice		Vcc 20V open output min. - ref. 5 max. 10 mA				
Open collector output		Requires external output resistors				
Output current / channel				± 20 mA		